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MODEL #

SCALE

N.T.S.

USSTW4-SE-8

REV. 0

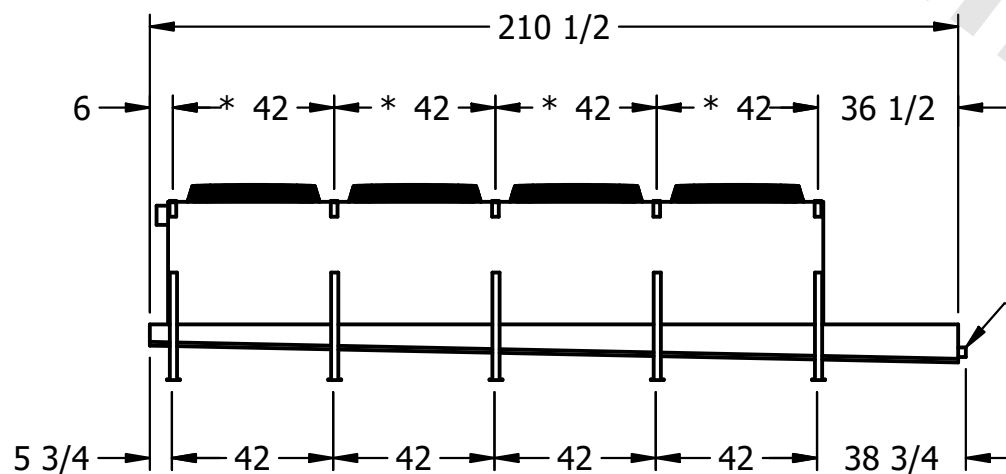
DATE	7/17/2026
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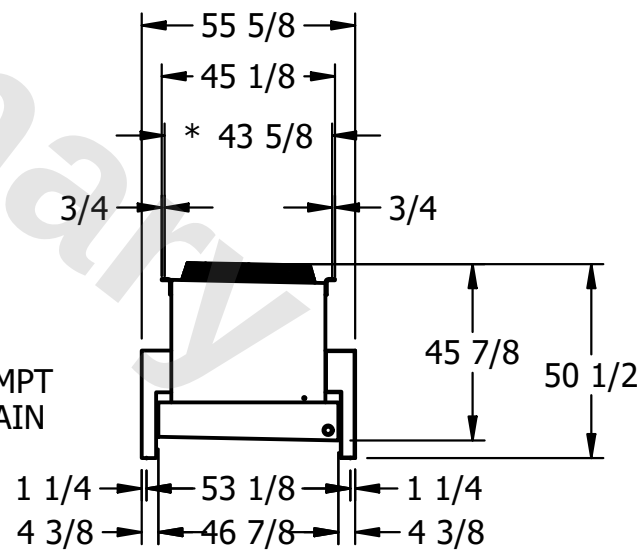
A schematic diagram of a four-wheeled mobile robot. It features a central rectangular body with a trapezoidal top section. Four wheels are positioned at the corners, each connected to a motor and gear system. Arrows indicate the direction of rotation for each wheel: the front-left and back-right wheels rotate clockwise, while the front-right and back-left wheels rotate counter-clockwise, suggesting a differential drive configuration.

- 1) * = HANGER HOLE LOCATION.
- 2) HANGER HOLES ARE FOR 3/4 INCH THREADED ROD.
- 3) ALL DIMENSIONS ARE FOR REFERENCE AND SHOULD NOT BE USED FOR PREFABRICATION OF PIPING OR SUPPORTS.

NEMA 4X
JUNCTION
BOX



- 2" MPT
DRAIN



ROOM

SHIPPING
WEIGHT

2370 lbs+ [1080] kg+

OPERATING WEIGHT	10000
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2710 lbs+ [1230] kg+